



# Fixed Point Theory for $(\mu, \psi)$ -Generalized Weakly Reich Contraction Mapping in Partially Ordered Metric Spaces

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## Abstract

In this paper we introduce a concept of  $(\mu, \psi)$ -generalized weakly Reich contraction mapping, and prove a fixed point theorem. Some Corollaries are consequences of the main result.

## 1 Introduction and Preliminaries

**Definition 1.1** ([1], [2], [3]). Let  $(X, d)$  be a metric space. A map  $T : X \mapsto X$  is called a weakly contractive mapping if for each  $x, y \in X$

$$d(Tx, Ty) \leq d(x, y) - \psi(d(x, y))$$

where  $\psi : [0, \infty) \mapsto [0, \infty)$  is continuous and non-decreasing,  $\psi(x) = 0$  if and only if  $x = 0$  and  $\lim \psi(x) = \infty$ .

**Remark 1.2.** If we take  $\psi(x) = kx$ ,  $0 < k < 1$ , in the above definition, then a weakly contractive mapping is called a contraction.

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**Definition 1.3** ([4]). Let  $(X, d)$  be a metric space. A map  $T : X \mapsto X$  is called a  $f$ -weakly contractive mapping if for each  $x, y \in X$ ,

$$d(Tx, Ty) \leq d(fx, fy) - \psi(d(fx, fy))$$

where  $f : X \mapsto X$  is a self-mapping,  $\psi : [0, \infty) \mapsto [0, \infty)$  is continuous and non-decreasing,  $\psi(x) = 0$  if and only if  $x = 0$  and  $\lim_{x \rightarrow \infty} \psi(x) = \infty$ .

**Remark 1.4.** If we take  $\psi(x) = (1 - k)x$ ,  $0 < k < 1$  in the above definition, then a  $f$ -weakly contractive mapping is called a  $f$ -contraction. Further, if  $f$  is the identity mapping and  $\psi(x) = (1 - k)x$ ,  $0 < k < 1$ , then a  $f$ -weakly contractive mapping is called a contraction.

**Definition 1.5** ([5]). Let  $(X, d)$  be a metric space. A map  $T : X \mapsto X$  is called a generalized  $f$ -weakly contractive mapping if for each  $x, y \in X$ ,

$$d(Tx, Ty) \leq \frac{1}{2}[d(fx, Ty) + d(fy, Tx)] - \psi(d(fx, Ty), d(fy, Tx))$$

where  $f : X \mapsto X$  is a self-mapping,  $\psi : [0, \infty)^2 \mapsto [0, \infty)$  is a continuous mapping such that  $\psi(x, y) = 0$  if and only if  $x = y = 0$ .

**Remark 1.6** ([2]). If  $f$  is the identity mapping in the above definition, then generalized  $f$ -weakly contractive mapping is a generalized weakly contractive mapping.

**Definition 1.7** ([6]). A function  $\mu : [0, \infty) \mapsto [0, \infty)$  is called an altering distance function if the following properties are satisfied

- (a)  $\mu$  is monotone increasing and continuous;
- (b)  $\mu(t) = 0$  if and only if  $t = 0$ .

**Definition 1.8** ([7]). Let  $(X, d)$  be a metric space. A map  $T : X \mapsto X$  is called a  $(\mu, \psi)$ -generalized  $f$ -weakly contractive mapping if for each  $x, y \in X$

$$\mu(d(Tx, Ty)) \leq \mu\left(\frac{1}{2}[d(fx, Ty) + d(fy, Tx)]\right) - \psi(d(fx, Ty), d(fy, Tx))$$

where  $f : X \mapsto X$  is a self-mapping,  $\mu : [0, \infty) \mapsto [0, \infty)$  is an altering distance function and  $\psi : [0, \infty)^2 \mapsto [0, \infty)$  is a lower semi-continuous mapping such that  $\psi(x, y) = 0$  if and only if  $x = y = 0$ .

**Remark 1.9.** If  $f$  is the identity mapping in the above definition, then a  $(\mu, \psi)$ -generalized  $f$ -weakly contractive mapping is a  $(\mu, \psi)$ -generalized weakly contractive mapping.

**Definition 1.10** ([8]). Let  $M$  be a nonempty subset of a metric space  $(X, d)$ . A point  $x \in M$  is a common fixed (coincidence) point of  $f$  and  $T$  if  $x = fx = Tx$  ( $fx = Tx$ ).

**Definition 1.11** ([8]). Let  $M$  be a nonempty subset of a metric space  $(X, d)$ .  $T, f : M \mapsto M$  are called commuting if  $Tfx = fTx$  for all  $x \in M$ .

**Definition 1.12** ([8]). Let  $M$  be a nonempty subset of a metric space  $(X, d)$ .  $T, f : M \mapsto M$  are called compatible if  $\lim d(Tfx_n, fTx_n) = 0$  whenever  $\{x_n\}$  is a sequence such that  $\lim Tx_n = \lim fx_n = t$  for some  $t$  in  $M$ .

**Definition 1.13** ([8]). Let  $M$  be a nonempty subset of a metric space  $(X, d)$ .  $T, f : M \mapsto M$  are called weakly compatible if they commute at their coincidence points, that is,  $Tfx = fTx$  whenever  $fx = Tx$ .

**Definition 1.14** ([8]). Let  $(X, \leq)$  be a partially ordered set and  $T, f : X \mapsto X$ . A mapping  $T$  is said to be monotone  $f$ -nondecreasing if for all  $x, y \in X$ ,  $fx \leq fy$  implies  $Tx \leq Ty$ .

**Remark 1.15.** If  $f$  is the identity mapping in the above definition, then  $T$  is monotone non-decreasing.

**Definition 1.16** ([8]). A subset  $W$  of a partially ordered set  $X$  is said to be well-ordered if every two elements of  $W$  are comparable.

## 2 Main Result

**Definition 2.1.** A map  $T : X \mapsto X$  will be called  $(\mu, \psi)$ -generalized weakly Reich contractive if for each  $x, y \in X$

$$\begin{aligned} \mu(d(Tx, Ty)) \leq & \mu\left(\frac{1}{3}[d(fx, Tx) + d(fy, Ty) + d(fx, fy)]\right) \\ & - \psi(d(fx, Tx), d(fy, Ty), d(fx, fy)) \end{aligned}$$

where

- (a)  $\mu : [0, \infty) \mapsto [0, \infty)$  is an altering distance function;
- (b)  $\psi : [0, \infty)^3 \mapsto [0, \infty)$  is a lower semi-continuous function with  $\psi(x, y, z) = 0$  if and only if  $x = y = z = 0$ .

**Theorem 2.2.** Let  $(X, \leq)$  be a partially ordered set and suppose that there exists a metric  $d$  on  $X$  such that  $(X, d)$  is a complete metric space. Suppose that  $T$  and  $f$  are self-mappings on  $X$ ,  $T(X) \subseteq f(X)$ ,  $T$  is a monotone  $f$ -nondecreasing mapping and

$$\begin{aligned} \mu(d(Tx, Ty)) \leq & \mu\left(\frac{1}{3}[d(fx, Tx) + d(fy, Ty) + d(fx, fy)]\right) \\ & - \psi(d(fx, Tx), d(fy, Ty), d(fx, fy)) \end{aligned}$$

where

- (a)  $\mu : [0, \infty) \mapsto [0, \infty)$  is an altering distance function;
- (b)  $\psi : [0, \infty)^3 \mapsto [0, \infty)$  is a lower semi-continuous function with  $\psi(x, y, z) = 0$  if and only if  $x = y = z = 0$ .

If  $\{fx_n\} \subset X$  is a nondecreasing sequence with  $fx_n \rightarrow f(z)$  in  $f(X)$ , then  $fx_n \leq f(z)$  and  $f(z) \leq f(f(z))$  for every  $n$ . Also, suppose that  $f(X)$  is closed. If there exists an  $x_0 \in X$  with  $fx_0 \leq Tx_0$ , then  $T$  and  $f$  have a coincidence

point. Further, if  $T$  and  $f$  are weakly compatible, then  $T$  and  $f$  have a common fixed point. Moreover, the set of common fixed points of  $T$  and  $f$  is well-ordered if and only if  $T$  and  $f$  have one and only one common fixed point.

*Proof.* Let  $x_0 \in X$  such that  $f(x_0) \leq T(x_0)$ . Since  $T(X) \subseteq f(X)$  we can choose  $x_1 \in X$  so that  $f x_1 = T x_0$ . Since  $T x_1 \in f(X)$ , there exists  $x_2 \in X$  such that  $f x_2 = T x_1$ . By induction, we can construct a sequence  $\{x_n\} \in X$  such that  $f x_{n+1} = T x_n$ , for every  $n \geq 0$ . Since  $f(x_0) \leq T(x_0)$ ,  $T x_0 = f x_1$ ,  $f(x_0) \leq f(x_1)$ ,  $T$  is monotone  $f$ -nondecreasing mapping,  $T(x_0) \leq T(x_1)$ . Similarly,  $f(x_1) \leq f(x_2)$ ,  $T(x_1) \leq T(x_2)$ ,  $f(x_2) \leq f(x_3)$ . Continuing, we obtain

$$T(x_0) \leq T(x_1) \leq T(x_2) \leq \dots \leq T(x_n) \leq T(x_{n+1}) \leq \dots$$

We suppose that  $d(Tx_n, Tx_{n+1}) > 0$  for all  $n$ . If not, then  $Tx_{n+1} = Tx_n$  for some  $n$ ,  $Tx_{n+1} = fx_{n+1}$ , that is,  $T$  and  $f$  have a coincidence point  $x_{n+1}$ , and so we have the result. Now we have

$$\begin{aligned} \mu(d(Tx_{n+1}, Tx_n)) &\leq \mu\left(\frac{1}{3}[d(fx_{n+1}, Tx_{n+1}) + d(fx_n, Tx_n) + d(fx_{n+1}, fx_n)]\right) \\ &\quad - \psi(d(fx_{n+1}, Tx_{n+1}), d(fx_n, Tx_n), d(fx_{n+1}, fx_n)) \\ &\leq \mu\left(\frac{1}{3}[d(Tx_n, Tx_{n+1}) + d(Tx_{n-1}, Tx_n) + d(Tx_n, Tx_{n-1})]\right) \\ &\quad - \psi(d(Tx_n, Tx_{n+1}), d(Tx_{n-1}, Tx_n), d(Tx_n, Tx_{n-1})) \\ &\leq \mu\left(\frac{1}{3}[d(Tx_n, Tx_{n+1}) + d(Tx_{n-1}, Tx_n) + d(Tx_n, Tx_{n-1})]\right) \\ &\leq \mu\left(\frac{1}{3}[3d(Tx_n, Tx_{n-1})]\right) \\ &= \mu(d(Tx_n, Tx_{n-1})). \end{aligned}$$

Since  $\mu$  is a non-decreasing function for all  $n = 1, 2, \dots$ , we have  $d(Tx_{n+1}, Tx_n) \leq d(Tx_n, Tx_{n-1})$ . Thus,  $\{d(Tx_{n+1}, Tx_n)\}$  is a monotone decreasing sequence of non-negative real numbers and hence is convergent. Hence there exists  $r \geq 0$  such

that  $d(Tx_{n+1}, Tx_n) \rightarrow r$ . Now, since

$$\begin{aligned} \mu(d(Tx_{n+1}, Tx_n)) &\leq \mu\left(\frac{1}{3}[d(Tx_n, Tx_{n+1}) + d(Tx_{n-1}, Tx_n) + d(Tx_n, Tx_{n-1})]\right) \\ &\quad - \psi(d(Tx_n, Tx_{n+1}), d(Tx_{n-1}, Tx_n), d(Tx_n, Tx_{n-1})). \end{aligned}$$

If we take limits in the above inequality as  $n \rightarrow \infty$  we get that

$$\begin{aligned} \mu(r) &\leq \mu\left(\frac{1}{3}(r + r + r)\right) - \psi(r, r, r) \\ &= \mu(r) - \psi(r, r, r) \end{aligned}$$

which implies that  $\psi(r, r, r) \leq 0$ . Thus  $r = 0$ , and hence  $\lim_{n \rightarrow \infty} d(Tx_{n+1}, Tx_n) = 0$ . Now we show that  $\{Tx_n\}$  is a Cauchy sequence. If otherwise, then there exist  $\epsilon > 0$  for which we can find subsequences  $\{Tx_{m(k)}\}$  and  $\{Tx_{n(k)}\}$  of  $\{Tx_n\}$  with  $n(k) > m(k) > k$  such that for every  $k$ ,  $d(Tx_{m(k)}, Tx_{n(k)}) \geq \epsilon$ ,  $d(Tx_{m(k)}, Tx_{n(k)-1}) < \epsilon$ . So we have,

$$\begin{aligned} \epsilon &\leq d(Tx_{m(k)}, Tx_{n(k)}) \\ &\leq d(Tx_{m(k)}, Tx_{n(k)-1}) + d(Tx_{n(k)-1}, Tx_{n(k)}) \\ &\leq \epsilon + d(Tx_{n(k)-1}, Tx_{n(k)}). \end{aligned}$$

Letting  $n \rightarrow \infty$  and using  $d(Tx_{n-1}, Tx_n) \rightarrow 0$ , we have,  $\lim d(Tx_{m(k)}, Tx_{n(k)}) = \epsilon = \lim d(Tx_{m(k)}, Tx_{n(k)-1})$ . Now we have

$$\begin{aligned} \mu(\epsilon) &\leq \mu(d(Tx_{m(k)}, Tx_{n(k)})) \\ &\leq \mu\left(\frac{1}{3}[d(Tx_{m(k)}, Tx_{m(k)}) + d(Tx_{n(k)}, Tx_{n(k)}) + d(Tx_{m(k)}, Tx_{n(k)})]\right) \\ &\quad - \psi(d(Tx_{m(k)}, Tx_{m(k)}), d(Tx_{n(k)}, Tx_{n(k)}), d(Tx_{m(k)}, Tx_{n(k)})) \end{aligned}$$

which implies that

$$\begin{aligned} \mu(\epsilon) &\leq \mu(d(Tx_{m(k)}, Tx_{n(k)})) \\ &\leq \mu\left(\frac{1}{3}[d(Tx_{m(k)-1}, Tx_{m(k)}) + d(Tx_{n(k)-1}, Tx_{n(k)}) + d(Tx_{m(k)-1}, Tx_{n(k)-1})]\right) \\ &\quad - \psi(d(Tx_{m(k)-1}, Tx_{m(k)}), d(Tx_{n(k)-1}, Tx_{n(k)}), d(Tx_{m(k)-1}, Tx_{n(k)-1})). \end{aligned}$$

If we take limits in the above inequality and using the fact that  $\lim_{n \rightarrow \infty} d(Tx_{n+1}, Tx_n) = 0$  we deduce the following

$$\begin{aligned} \mu(\epsilon) &\leq \mu\left(\frac{1}{3}[0 + 0 + \epsilon]\right) - \psi(0, 0, \epsilon) \\ &= \mu\left(\frac{1}{3}\epsilon\right) - \psi(0, 0, \epsilon) \\ &\leq \mu(\epsilon) - \psi(0, 0, \epsilon) \end{aligned}$$

which implies that  $\psi(0, 0, \epsilon) \leq 0$ , which is a contradiction since  $\epsilon > 0$ . Hence  $\{Tx_n\}$  is a Cauchy sequence and therefore is convergent in the complete metric space  $(X, d)$ . As  $f(X)$  is closed and  $fx_n = Tx_{n-1}$ ,  $\{fx_n\}$  is also a Cauchy sequence, there is some  $z \in X$  such that  $\lim fx_{n+1} = \lim Tx_n = fz$ . Since  $\{fx_n\}$  is a non-decreasing sequence and  $\lim fx_{n+1} = fz$ ,  $f(x_n) \leq f(z)$  and  $f(z) \leq f(f(z))$  for every  $n$ . Now we have

$$\begin{aligned} \mu(d(Tz, fx_{n+1})) &= \mu(d(Tz, Tx_n)) \\ &\leq \mu\left(\frac{1}{3}[d(fz, Tz) + d(fx_n, Tx_n) + d(fz, fx_n)]\right) \\ &\quad - \psi(d(fz, Tz), d(fx_n, Tx_n), d(fz, fx_n)) \\ &= \mu\left(\frac{1}{3}[d(fz, Tz) + d(fx_n, fx_{n+1}) + d(fz, fx_n)]\right) \\ &\quad - \psi(d(fz, Tz), d(fx_n, fx_{n+1}), d(fz, fx_n)). \end{aligned}$$

Now taking limits as  $n \rightarrow \infty$  we deduce the following

$$\begin{aligned} \mu(d(Tz, fz)) &\leq \mu\left(\frac{1}{3}d(fz, Tz)\right) - \psi(d(fz, Tz), 0, 0) \\ &\leq \mu\left(d(fz, Tz)\right) - \psi(d(fz, Tz), 0, 0) \end{aligned}$$

which implies  $\psi(d(fz, Tz), 0, 0) \leq 0$ . Hence,  $d(fz, Tz) = 0$ , thus,  $fz = Tz$ , and hence  $z$  is a coincidence point of  $T$  and  $f$ . Now suppose that  $T$  and  $f$  are weakly compatible. Let  $w = T(z) = f(z)$ , then  $T(w) = T(f(z)) = f(T(z)) = f(w)$  and

$f(z) \leq f(f(z)) = f(w)$ . Now we have,

$$\begin{aligned} \mu(d(Tz, Tw)) &\leq \mu\left(\frac{1}{3}[d(fz, Tz) + d(fw, Tw) + d(fz, fw)]\right) \\ &\quad - \psi(d(fz, Tz), d(fw, Tw), d(fz, fw)) \\ &= \mu\left(\frac{1}{3}[d(Tz, Tz) + d(Tw, Tw) + d(Tz, Tw)]\right) \\ &\quad - \psi(d(Tz, Tz), d(Tw, Tw), d(Tz, Tw)) \\ &= \mu\left(\frac{1}{3}d(Tz, Tw)\right) - \psi(0, 0, d(Tz, Tw)) \\ &\leq \mu\left(d(Tz, Tw)\right) - \psi(0, 0, d(Tz, Tw)) \end{aligned}$$

which implies that  $\psi(0, 0, d(Tz, Tw)) \leq 0$ . Hence,  $d(Tz, Tw) = 0$ . Therefore,  $Tw = fw = w$ . Now suppose that the set of common fixed points of  $T$  and  $f$  is well-ordered. We claim that the common fixed points of  $T$  and  $f$  is unique. Assume on contrary that,  $Tu = fu = u$  and  $Tv = fv = v$  but  $u \neq v$ . Now observe we have the following

$$\begin{aligned} \mu(d(u, v)) &= \mu(d(Tu, Tv)) \\ &\leq \mu\left(\frac{1}{3}[d(fu, Tu) + d(fv, Tv) + d(fu, fv)]\right) \\ &\quad - \psi(d(fu, Tu), d(fv, Tv), d(fu, fv)) \\ &\leq \mu\left(\frac{1}{3}[d(u, u) + d(v, v) + d(u, v)]\right) \\ &\quad - \psi(d(u, u), d(v, v), d(u, v)) \\ &= \mu\left(\frac{1}{3}[0 + 0 + d(u, v)]\right) - \psi(0, 0, d(u, v)) \\ &\leq \mu(d(u, v)) - \psi(0, 0, d(u, v)) \end{aligned}$$

which implies that  $\psi(0, 0, d(u, v)) \leq 0$ . Therefore  $d(u, v) = 0$ , and hence  $u = v$ . Conversely, if  $T$  and  $f$  have only one common fixed point, then the set of common fixed point of  $T$  and  $f$  being a singleton is well-ordered, and the proof is finished.  $\square$



**Corollary 2.3.** *Let  $(X, \leq)$  be a partially ordered set and suppose that there exists a metric  $d$  on  $X$  such that  $(X, d)$  is a complete metric space. Suppose that  $T$  is a self-mappings on  $X$ ,  $T$  is a monotone nondecreasing mapping and*

$$\mu(d(Tx, Ty)) \leq \mu\left(\frac{1}{3}[d(x, Tx) + d(y, Ty) + d(x, y)]\right) - \psi(d(x, Tx), d(y, Ty), d(x, y))$$

for all  $x, y \in X$  for which  $x \geq y$  where

- (a)  $\mu : [0, \infty) \mapsto [0, \infty)$  is an altering distance function;
- (b)  $\psi : [0, \infty)^3 \mapsto [0, \infty)$  is a lower semi-continuous function with  $\psi(x, y, z) = 0$  if and only if  $x = y = z = 0$ .

If either

- (i)  $\{x_n\} \subset X$  is a nondecreasing sequence with  $x_n \rightarrow z$  in  $X$ , then  $x_n \leq z$  for every  $n$  or
- (ii)  $T$  is continuous.

If there exists an  $x_0 \in X$  with  $x_0 \leq T(x_0)$ , then  $T$  has a fixed point. Moreover, for arbitrary two points  $x, y \in X$ , there exists  $w \in X$  such that  $w$  is comparable with both  $x$  and  $y$ , then the fixed point of  $T$  is unique.

*Proof.* If (i) holds, then taking  $f$  to be the identity mapping in the above theorem, we get the result. If (ii) holds, then proceeding as in the above theorem we can prove that  $\{Tx_n\}$  is a Cauchy sequence,  $z = \lim x_{n+1} = \lim T(x_n) = T(\lim x_n) = Tz$ , and hence  $T$  has a fixed point. Let  $u$  and  $v$  be two fixed points of  $T$  such that  $u \neq v$ . We consider two cases

(a) If  $u$  and  $v$  are comparable. We have

$$\begin{aligned}
 \mu(d(u, v)) &= \mu(d(Tu, Tv)) \\
 &\leq \mu\left(\frac{1}{3}[d(u, Tu) + d(v, Tv) + d(u, v)]\right) \\
 &\quad - \psi(d(u, Tu), d(v, Tv), d(u, v)) \\
 &\leq \mu\left(\frac{1}{3}[d(u, u) + d(v, v) + d(u, v)]\right) \\
 &\quad - \psi(d(u, u), d(v, v), d(u, v)) \\
 &= \mu\left(\frac{1}{3}[0 + 0 + d(u, v)]\right) - \psi(0, 0, d(u, v)) \\
 &\leq \mu(d(u, v)) - \psi(0, 0, d(u, v))
 \end{aligned}$$

which implies that  $\psi(0, 0, d(u, v)) \leq 0$ . Thus,  $d(u, v) = 0$ , hence  $u = v$ .

(b) If  $u$  and  $v$  are not comparable. Choose an element  $w \in X$  comparable with both of them. Then also  $u = T^n u$  is comparable to  $T^n w$  for each  $n$ . Now we have

$$\begin{aligned}
 \mu(d(u, T^n w)) &= \mu(d(T^n u, T^n w)) \\
 &= \mu(d(TT^{n-1}u, TT^{n-1}w)) \\
 &\leq \mu\left(\frac{1}{3}[d(T^{n-1}u, T^n u) + d(T^{n-1}w, T^n w) + d(T^{n-1}u, T^{n-1}w)]\right) \\
 &\quad - \psi(d(T^{n-1}u, T^n u), d(T^{n-1}w, T^n w), d(T^{n-1}u, T^{n-1}w)) \\
 &\leq \mu\left(\frac{1}{3}[d(u, u) + d(T^{n-1}w, T^n w) + d(u, T^{n-1}w)]\right) \\
 &\quad - \psi(d(u, u), d(T^{n-1}w, T^n w), d(u, T^{n-1}w))
 \end{aligned}$$

$$\begin{aligned}
 &\leq \mu\left(\frac{1}{3}[0 + d(T^{n-1}w, T^n w) + d(u, T^{n-1}w)]\right) \\
 &\quad - \psi(0, d(T^{n-1}w, T^n w), d(u, T^{n-1}w)) \\
 &\leq \mu\left(\frac{1}{3}[d(T^{n-1}w, u) + d(u, T^n w) + d(u, T^{n-1}w)]\right) \\
 &\leq \mu\left(\frac{1}{3}[3d(u, T^{n-1}w)]\right) \\
 &= \mu(d(u, T^{n-1}w))
 \end{aligned}$$

and hence we get  $d(u, T^n w) \leq d(u, T^{n-1}w)$ . This proves that the nonnegative decreasing sequence  $\{d(u, T^n w)\}$  is convergent. Let  $d(u, T^n w) \rightarrow r$ . Since,

$$\begin{aligned}
 \mu(d(u, T^n w)) &= \mu(d(T^n u, T^n w)) \\
 &\leq \mu\left(\frac{1}{3}[0 + d(T^{n-1}w, T^n w) + d(u, T^{n-1}w)]\right) \\
 &\quad - \psi(0, d(T^{n-1}w, T^n w), d(u, T^{n-1}w)).
 \end{aligned}$$

If we take limits in the above inequality as  $n \rightarrow \infty$  we get that

$$\begin{aligned}
 \mu(r) &\leq \mu\left(\frac{1}{3}(0 + 2r + r)\right) - \psi(0, 2r, r) \\
 &= \mu(r) - \psi(0, 2r, r)
 \end{aligned}$$

which implies that  $\psi(0, 2r, r) \leq 0$ . Thus  $r = 0$ , and hence  $d(u, T^n w) \rightarrow 0$ . Analogously, it can be proved that  $d(v, T^n w) \rightarrow 0$ . Since the limit is unique we get that  $u = v$ .

□

If  $\mu(t) = t$ , then we have the following result

**Corollary 2.4.** *Let  $(X, \leq)$  be a partially ordered set and suppose that there exists a metric  $d$  on  $X$  such that  $(X, d)$  is a complete metric space. Suppose that  $T$  is a self-mappings on  $X$ ,  $T$  is a monotone nondecreasing mapping and*

$$d(Tx, Ty) \leq \frac{1}{3}[d(x, Tx) + d(y, Ty) + d(x, y)] - \psi(d(x, Tx), d(y, Ty), d(x, y))$$

for all  $x, y \in X$  for which  $x \geq y$  where

- (a)  $\mu : [0, \infty) \mapsto [0, \infty)$  is an altering distance function;
- (b)  $\psi : [0, \infty)^3 \mapsto [0, \infty)$  is a lower semi-continuous function with  $\psi(x, y, z) = 0$  if and only if  $x = y = z = 0$ .

If either

- (i)  $\{x_n\} \subset X$  is a nondecreasing sequence with  $x_n \rightarrow z$  in  $X$ , then  $x_n \leq z$  for every  $n$  or
- (ii)  $T$  is continuous.

If there exists an  $x_0 \in X$  with  $x_0 \leq T(x_0)$ , then  $T$  has a fixed point. Moreover, for arbitrary two points  $x, y \in X$ , there exists  $w \in X$  such that  $w$  is comparable with both  $x$  and  $y$ , then the fixed point of  $T$  is unique.

If  $\psi(x, y, z) = \left(\frac{1}{3} - k\right)(x + y + z)$ , then we have the following result

**Corollary 2.5.** *Let  $(X, \leq)$  be a partially ordered set and suppose that there exists a metric  $d$  on  $X$  such that  $(X, d)$  is a complete metric space. Suppose that  $T$  is a non-decreasing self-mapping of  $X$ , and  $T$  satisfies*

$$d(Tx, Ty) \leq k[d(x, Tx) + d(y, Ty) + d(x, y)]$$

for all  $x, y \in X$  for which  $x \geq y$  where  $0 < k < \frac{1}{3}$ . If either

- (i)  $\{x_n\} \subset X$  is a nondecreasing sequence with  $x_n \rightarrow z$  in  $X$ , then  $x_n \leq z$  for every  $n$  or
- (ii)  $T$  is continuous.

If there exists an  $x_0 \in X$  with  $x_0 \leq T(x_0)$ , then  $T$  has a fixed point.

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