

The Modified Power Series Inverted Exponentiated Generalized Class of Distributions: Statistical Measures, Model Fit, and Characterization

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Abstract

Within the master thesis [1], the author considered the following random variable

$$T = X^{-1} - 1,$$

where X follows the Kumaraswamy distribution, and obtains a so-called inverted Kumaraswamy distribution, and studies some properties and applications of this class of distributions in the context of the power series family [2]. Within the paper [3], they introduced the exponentiated generalized class of distributions and obtained some properties with applications. Based on these developments we introduce a class of modified power series inverted exponentiated generalized distributions and obtain some of their properties with applications. Some characterization theorems are also presented. Avenues for further research concludes the paper.

1 Introduction

The exponentiated class of distributions first appeared in [4], with the following representation for its CDF

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$$F(x)^{\beta},$$

where F(x) is some baseline distribution and $\beta > 0$. An extension of this distribution inspired by the Kumaraswamy's double bounded distribution [5] appeared in [6] with the following representation for its CDF

$$1 - (1 - F(x)^a)^b$$
,

where F(x) is some baseline distribution with a, b > 0. If we exponentiate the above CDF, and take a = 1, then we get the following CDF introduced in [3]

$$(1 - (1 - F(x))^{\alpha})^{\beta},$$

where $\alpha, \beta > 0$.

It is well known that the inverse distribution is the distribution of the reciprocal of a random variable [8]. If we consider the random variable $Y = \frac{1}{X}$, where X has CDF F(x), then the reciprocal distribution, $F_Y(y)$ has CDF

$$1 - F_X\left(\frac{1}{y}\right).$$

In some recent works, authors have considered the following modification of the transformation $Y = \frac{1}{X}$, that is

$$Y^* = \frac{1}{X} - 1,$$

where X has CDF F(x). In this case, the reciprocal distribution, $F_{Y^*}(y^*)$ has CDF

$$F_{Y^*}(y^*) = 1 - F_X\left(\frac{1}{y^*+1}\right).$$

The power series class of distributions was proposed and studied in [2]. This class of distributions includes binomial, geometric, logarithmic and Poisson distributions as special cases. However, these distributions may not be useful when a random variable takes the value of zero with high probability, that is, zero-inflated. In such situations, it is more appropriate to consider the distribution which is truncated at zero.

Power series distributions are usually motivated by the stochastic representations

$$Z = \min(X_1, \cdots, X_N)$$

if the components are in series, or

$$Z = \max(X_1, \cdots, X_N)$$

if the components are in parallel, and many lifetime data admit such representations, and the related distributions are very useful in modeling such data. We suppose X_1, \dots, X_N are independent and identically distributed random variables from a parent distribution with PDF f(x) and CDF F(x), and consider N to be a discrete random variable from a power series distribution (truncated at zero) and whose PDF is given by

$$P(N=n) = \frac{a_n \lambda^n}{C(\lambda)}, \ n = 1, 2, 3, \cdots$$

where $C(\lambda) = \sum_{n=1}^{\infty} a_n \lambda^n$, a_n depends on n, and $\lambda > 0$. $C(\lambda)$ is finite, and its first, second, and third derivatives with respect to λ are defined and given by $C'(\lambda)$, $C''(\lambda)$, and $C'''(\lambda)$, respectively. The table below represents some useful quantities including a_n , $C(\lambda)$, $C^{-1}(\lambda)$, $C'(\lambda)$, $C''(\lambda)$, and $C'''(\lambda)$, respectively, for the Poisson, geometric, logarithmic and binomial (with m being the number of replicas) distributions which belong to the power series family of distributions.

Table 1: Useful quantities for some power series distributions.

Distribution	$C(\lambda)$	$C'(\lambda)$	$C''(\lambda)$	$C'''(\lambda)$	$C^{-1}(\lambda)$	a_n	Parameter Space
Poisson	$e^{\lambda} - 1$	e^{λ}	e^{λ}	e^{λ}	$\log(1+\lambda)$	$(n!)^{-1}$	$(0,\infty)$
Geometric	$\lambda(1-\lambda)^{-1}$	$(1-\lambda)^{-2}$	$2(1-\lambda)^{-3}$	$6(1-\lambda)^{-4}$	$\lambda(1+\lambda)^{-1}$	1	(0, 1)
Logarithmic	$-\log(1-\lambda)$	$(1 - \lambda)^{-1}$	$(1-\lambda)^{-2}$	$2(1-\lambda)^{-3}$	$1 - e^{-\lambda}$	n^{-1}	(0, 1)
Binomial	$(1+\lambda)^m - 1$	$\frac{m}{(1+\lambda)^{1-m}}$	$\frac{m(m-1)}{(1+\lambda)^{2-m}}$	$\frac{m(m-1)(m-2)}{(1+\lambda)^{3-m}}$	$(\lambda+1)^{\frac{1}{m}}-1$	$\binom{m}{n}$	$(0,\infty)$

If $X_{(1)} = \min\{X_1, \dots, X_N\}$, then the conditional CDF of $X_{(1)}|N = n$ is given by

$$F_{X_{(1)}|N=n}(x) = 1 - [1 - F(x)]^n.$$

The CDF of the power series class of distributions associated with some parent distribution with PDf f(x) and CDF F(x) is the marginal CDF of $X_{(1)}$, which is given by

$$1 - \frac{C(\lambda(1 - F(x)))}{C(\lambda)}.$$

From [3], the Exponentiated (Standard Uniform) Generalized distribution has cdf

$$F(x) = (1 - (1 - x)^{\alpha})^{\beta},$$

where $\alpha, \beta > 0$ are two additional shape parameters. Suppose X follows the Exponentiated Standard Uniform Generalized Distribution, and consider the transformation discussed earlier

$$Y^* = X^{-1} - 1.$$

By the transformation technique, the cdf of Y^* is given by

$$G(y^*) = 1 - \left[1 - \left(\frac{y^*}{y^* + 1}\right)^{\alpha}\right]^{\beta}$$

for $\alpha, \beta > 0$. The cdf above, represents the cdf of the Inverted Exponentiated (Standard Uniform) Generalized distribution.

Based on the stochastic representation $X_{(1)} = \min\{X_1, \dots, X_N\}$ we study some properties and applications of a certain modified power series inverted Exponentiated Generalized distribution (by relaxing the domain space of y^* - see new family defined). This manuscript is organized as follows. In Section 3, we present the PDF and CDF of the new family. In Section 4, we introduce some sub-models of the new family and demonstrate some of their reliablity properties visually. In Section 5, some statistical measures are presented, and they include expansion formulas for the CDF and PDF, quantile function, ordinary moments, Renyi entropy, moment generating function, stochastic ordering, incomplete moments, inequality measures, mean residual life, order statistics, and moments of order statistics. The representation of the distribution as a transformed random variable is also discussed. In Section 6, estimation of model parameters in the modified Poisson-X family of distributions is discussed. In Section 7 we assess the performance of the maximum likelihood method in estimating model parameters. For this, a sub-model of the broad family is considered, namely, the modified Poission inverted exponentiated generalized distribution (MPIEG), and a monte carlo simulation study is conducted. The result indicates that using the method of maximum likelihood in estimating model parameters is adequate. In Section 8, we show sub-models of the new family are useful in fitting real-life data coming from the chemical/material sciences. In Section 9, we present some characterizations of the Modified Poisson-X distribution. Section 10 concludes the paper, and some directions for further research are proposed.

3 The New Family Defined

The PDF of the new family is given by

$$\frac{\lambda f(x)C'(\lambda(1-F(x)))}{C(\lambda)},$$

where C and C' are some useful quantities from Table 1, and

$$F(x) = 1 - \left[1 - \left(\frac{x}{x+1}\right)^{\alpha}\right]^{\beta}$$

for $\alpha, \beta, x > 0$ with $f(x) = \frac{\partial F(x)}{\partial x}$. The CDF of the new family is given by

$$1 - \frac{C(\lambda(1 - F(x)))}{C(\lambda)}$$

where C is some useful quantity from Table 1, and F(x) is as given above. The parameter space for λ is $(-\infty, 0) \cup (0, \infty)$.

4 Some Sub-Models

We introduce four sub-models and visualize some of their basic reliability properties. The reliability properties include survival function (SF), hazard rate function(HF), and the cumulative hazard rate function (CHF).

4.1 Modified Poisson Inverted Exponentiated Generalized Distribution

The PDF of the Modified Poisson Inverted Exponentiated Generalized distribution is given by

$$P(x;\alpha,\beta,\lambda) = \frac{\alpha\beta\lambda x^{\alpha-1}(x+1)^{-\alpha-1}\left(1-\left(\frac{x}{x+1}\right)^{\alpha}\right)^{\beta-1}e^{\lambda\left(1-\left(\frac{x}{x+1}\right)^{\alpha}\right)^{\beta}}}{e^{\lambda}-1}$$

and the CDF is given by

$$p(x; \alpha, \beta, \lambda) = \frac{e^{\lambda} - e^{\lambda \left(1 - \left(\frac{x}{x+1}\right)^{\alpha}\right)^{\beta}}}{e^{\lambda} - 1}$$

The survival function, hazard rate function, and the cumulative hazard rate function, respectively, are given by

$$S(x; \alpha, \beta, \lambda) = 1 - P(x; \alpha, \beta, \lambda)$$
$$H(x; \alpha, \beta, \lambda) = \frac{p(x; \alpha, \beta, \lambda)}{1 - P(x; \alpha, \beta, \lambda)}$$

$$CHF(x; \alpha, \beta, \lambda) = -\log\left(S(x; \alpha, \beta, \lambda)\right).$$

Notation 4.1. We write

$$W^* \sim MPIEG(\alpha, \beta, \lambda)$$

if W^* is a Modified Poisson Inverted Exponentiated Generalized random variable.



Figure 1: The CDF(red), PDF(blue), SF(green), CHF(purple), and the HF(brown) of MPIEG(8.3, 20.5, -2.9).

4.2 Modified Geometric Inverted Exponentiated Generalized Distribution

The PDF of the Modified Geometric Inverted Exponentiated Generalized distribution is given by

$$g(x;\alpha,\beta,\lambda) = -\frac{\alpha\beta(\lambda-1)x^{\alpha-1}(x+1)^{-\alpha-1}\left(1-\left(\frac{x}{x+1}\right)^{\alpha}\right)^{\beta-1}}{\left(\lambda\left(1-\left(\frac{x}{x+1}\right)^{\alpha}\right)^{\beta}-1\right)^2}$$

and the CDF is given by

$$G(x; \alpha, \beta, \lambda) = \frac{1}{\lambda + \frac{\lambda - 1}{\left(1 - \left(\frac{x}{x+1}\right)^{\alpha}\right)^{\beta} - 1}}.$$

The survival function, hazard rate function, and the cumulative hazard rate function, respectively, are given by

$$S(x; \alpha, \beta, \lambda) = 1 - G(x; \alpha, \beta, \lambda)$$

$$H(x; \alpha, \beta, \lambda) = \frac{g(x; \alpha, \beta, \lambda)}{1 - G(x; \alpha, \beta, \lambda)}$$

$$CHF(x; \alpha, \beta, \lambda) = -\log\left(S(x; \alpha, \beta, \lambda)\right).$$

Notation 4.2. We write

$$W^{**} \sim MGIEG(\alpha, \beta, \lambda)$$

if W^{**} is a Modified Geometric Inverted Exponentiated Generalized random variable.



Figure 2: The CDF(red), PDF(blue), SF(green), CHF(purple), and the HF(brown) of MGIEG(5.2, 15.5, -30.3).

4.3 Modified Binomial Inverted Exponentiated Generalized Distribution

Here we assume the number of replicas is given by m = 2. Thus, the PDF of the Modified Binomial Inverted Exponentiated Generalized distribution is given by

$$b(x;\alpha,\beta,\lambda) = \frac{2\alpha\beta x^{\alpha-1}(x+1)^{-\alpha-1}\left(1-\left(\frac{x}{x+1}\right)^{\alpha}\right)^{\beta-1}\left(\lambda\left(1-\left(\frac{x}{x+1}\right)^{\alpha}\right)^{\beta}+1\right)}{\lambda+2}$$

and the CDF is given by

$$B(x;\alpha,\beta,\lambda) = 1 - \frac{\left(\lambda \left(1 - \left(\frac{x}{x+1}\right)^{\alpha}\right)^{\beta} + 1\right)^{2} - 1}{\lambda(\lambda+2)}$$

The survival function, hazard rate function, and the cumulative hazard rate function, respectively, are given by

$$S(x; \alpha, \beta, \lambda) = 1 - B(x; \alpha, \beta, \lambda)$$
$$H(x; \alpha, \beta, \lambda) = \frac{b(x; \alpha, \beta, \lambda)}{1 - B(x; \alpha, \beta, \lambda)}$$
$$CHF(x; \alpha, \beta, \lambda) = -\log\left(S(x; \alpha, \beta, \lambda)\right)$$

Notation 4.3. We write

$$W^{***} \sim MBIEG(\alpha, \beta, \lambda)$$

if W^{***} is a Modified Binomial Inverted Exponentiated Generalized random variable.



Figure 3: The CDF(red), PDF(blue), SF(green), CHF(purple), and the HF(brown) of MBIEG(10.2,25.8,-0.7).

4.4 Modified Logarithmic Inverted Exponentiated Generalized Distribution

The PDF of the Modified Logarithmic Inverted Exponentiated Generalized distribution is given by

$$l(x;\alpha,\beta,\lambda) = \frac{\alpha\beta\lambda x^{\alpha-1}(x+1)^{-\alpha-1}\left(1-\left(\frac{x}{x+1}\right)^{\alpha}\right)^{\beta-1}}{\log(1-\lambda)\left(1-\lambda\left(1-\left(\frac{x}{x+1}\right)^{\alpha}\right)^{\beta}\right)}$$

and the CDF is given by

$$L(x; \alpha, \beta, \lambda) = 1 - \frac{\log\left(1 - \lambda\left(1 - \left(\frac{x}{x+1}\right)^{\alpha}\right)^{\beta}\right)}{\log(1 - \lambda)}.$$

The survival function, hazard rate function, and the cumulative hazard rate function, respectively, are given by

$$S(x; \alpha, \beta, \lambda) = 1 - L(x; \alpha, \beta, \lambda)$$

$$H(x; \alpha, \beta, \lambda) = \frac{l(x; \alpha, \beta, \lambda)}{1 - L(x; \alpha, \beta, \lambda)}$$

$$CHF(x; \alpha, \beta, \lambda) = -\log\left(S(x; \alpha, \beta, \lambda)\right).$$

Notation 4.4. We write

$$W^{****} \sim MLIEG(\alpha, \beta, \lambda)$$

if W^{****} is a Modified Logarithmic Inverted Exponentiated Generalized random variable.



Figure 4: The CDF(red), PDF(blue), SF(green), CHF(purple), and the HF(brown) of MLIEG(8.9, 34.1, -53.8).

5 Some Statistical Measures

Here we obtain some properties for the Modified Poisson-X distribution, that is, we consider

$$1 - \frac{C(\lambda(1 - F(x)))}{C(\lambda)}$$

with $C(\lambda) = e^{\lambda} - 1$.

Explicitly, the CDF can be written as

$$1 - \frac{e^{\lambda(1 - F(x))} - 1}{e^{\lambda} - 1},$$

where $\lambda \in (-\infty, 0) \cup (0, \infty)$ and F(x) is some baseline CDF.

5.1 CDF Power Series

Theorem 5.1. The CDF of the Modified Poisson-X distribution admit the following representation

$$\frac{e^{\lambda} - \sum_{k=0}^{\infty} \sum_{q=0}^{k} \frac{\lambda^{k}}{k!} {k \choose q} (-1)^{q} F(x)^{q}}{e^{\lambda} - 1},$$

where $\lambda \in (-\infty, 0) \cup (0, \infty)$ and F(x) is some baseline CDF.

5.2 PDF Power Series

By differentiation, the PDF of the Modified Poisson-X family is given by

$$\frac{\lambda}{e^{\lambda} - 1} f(x) e^{\lambda(1 - F(x))}.$$

Theorem 5.2. The PDF of the Modified Poisson-X distribution admit the following representation

$$\frac{\lambda^{k+1}}{(e^{\lambda}-1)k!} \sum_{k=0}^{\infty} \sum_{q=0}^{k} (-1)^q \binom{k}{q} f(x) F(x)^q,$$

where $\lambda \in (-\infty, 0) \cup (0, \infty)$, and the random variable X has PDF f(x) and CDF F(x).

5.3 Transformation of Random Variables

Theorem 5.3. Let U be a random variable uniform on [0, 1). Then the following random variable follows the Modified Poisson-X class of distributions

$$X = Q_F \left[\frac{\lambda - \log((e^{\lambda} - 1)(1 - U))}{\lambda} \right],$$

where $Q_F = F^{-1}(\cdot)$ is the quantile function of the distribution with CDF F, and $\lambda \in (-\infty, 0) \cup (0, \infty)$.

5.4 Quantile Function

Theorem 5.4. The quantile function of the Modified Poisson-X class of distributions is given by

$$Q_F\left[\frac{\lambda - \log((e^{\lambda} - 1)(1 - p))}{\lambda}\right],$$

where $Q_F = F^{-1}(\cdot)$ is the quantile function of the distribution with CDF F, $\lambda \in (-\infty, 0) \cup (0, \infty)$, and 0 .



Figure 5: The quantile function of Modified Poisson-Standard Uniform for $0 < \lambda < 10$ and 0 .

5.5 Ordinary Moments

If X is standard uniform, then the PDF of the Modified Poisson-Standard Uniform distribution is given by

$$\frac{\lambda}{e^{\lambda} - 1} e^{\lambda(1 - x)}$$

for $x \in [0,1]$ and $\lambda \in (-\infty,0) \cup (0,\infty)$. Thus we have the following

Theorem 5.5. The ordinary moments of the Modified Poisson-Standard Uniform class of distributions are given by

$$\mu'_r = \frac{\lambda}{e^{\lambda} - 1} e^{\lambda} \lambda^{-r-1} (\Gamma(r+1) - \Gamma(r+1,\lambda)),$$

where $r \in \mathbb{N}$, $\lambda \in (-\infty, 0) \cup (0, \infty)$, $\Gamma(\cdot)$ is the Euler Gamma function, and $\Gamma(\cdot, \cdot)$ is the incomplete gamma function.

Remark 5.6. By definition,

$$\Gamma(z) = \int_0^\infty t^{z-1} e^{-t} dt$$

and

$$\Gamma(a,z) = \int_{z}^{\infty} t^{a-1} e^{-t} dt.$$

Table 2: Some values of the ordinary moments of the Modified Poisson-Standard Uniform distribution for some choice parameter λ .

μ'_r	$\lambda = 0.5$	$\lambda = 2.5$
μ'_1	0.458506	0.310575
μ_2'	0.29253	0.159034
μ'_3	0.213683	0.101415
μ'_4	0.167973	0.0728392
μ_5'	0.13824	0.056253

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5.6 Renyi Entropy

Let X be a random variable with PDF f(x). By definition, the Renyi entropy [9] is defined as

$$I_R(\delta) = \frac{1}{1-\delta} Log\left(\int_{-\infty}^{\infty} f^{\delta}(x) dx\right),$$

where $\delta > 0$, and $\delta \neq 1$. The main result of this section is the following whose proof is omitted.

Theorem 5.7. The Renyi entropy of the Modified Poisson-X family of distributions can be expressed as

$$I_R(\delta) = \frac{1}{1-\delta} \log\left[\left(\frac{\lambda}{e^{\lambda}-1}\right)^{\delta} \sum_{k=0}^{\infty} \sum_{m=0}^{k} \omega_{k,m} \int_{-\infty}^{\infty} f(x)^{\delta} F(x)^m dx\right],$$

where the random variable X has CDF F(x) and PDF f(x), $1 \neq \delta > 0$, $\lambda \in (-\infty, 0) \cup (0, \infty)$, and

$$\omega_{k,m} = \binom{k}{m} \frac{\delta^k \lambda^k (-1)^m}{k!}.$$

Table 3: The Renyi entropy of the Modified Poisson-Standard Uniform distribution for some choice parameter λ .

$I_R(\delta)$	$\lambda = 0.5$	$\lambda = 2.5$
$I_{R}(0.2)$	-0.00207797	-0.0490209
$I_{R}(0.7)$	-0.00725856	-0.163813
$I_{R}(1.3)$	-0.0134301	-0.281075
$I_{R}(1.5)$	-0.0154721	-0.314715
$I_R(2.7)$	-0.0274999	-0.467369

5.7 Moment Generating Function

Given a random variable X, one defines the moment generating function as

$$M_X(z) = E[e^{zX}],$$

where $E[\cdot]$ is an expectation. Now using the series expansion for e^{zX} , one can write

$$M_X(z) = \sum_{r=0}^{\infty} \frac{z^r \mu'_r}{r!},$$

where μ'_r is the *r*th non-central moment of the random variable X. Thus from Theorem 5.5, the following is an immediate consequence

Theorem 5.8. The moment generating function of the Modified Poisson-Standard Uniform class of distributions is given by

$$M_X(z) = \sum_{r=0}^{\infty} \frac{z^r \lambda}{r!(e^{\lambda} - 1)} e^{\lambda} \lambda^{-r-1} (\Gamma(r+1) - \Gamma(r+1,\lambda)),$$

where $\lambda \in (-\infty, 0) \cup (0, \infty)$, $\Gamma(\cdot)$ is the Euler Gamma function, and $\Gamma(\cdot, \cdot)$ is the incomplete gamma function.

5.8 Stochastic Ordering

Stochastic ordering is a common concept to show the ordering mechanism in lifetime distributions [10]. A random variable X is said to be stochastically smaller than the random variable Y in the likelihood ratio order $(X \leq_{l_r} Y)$ if the ratio of the associated PDFs given by $\frac{f_X(x)}{f_Y(x)}$ decreases in x. The main result is the following whose proof we omit.

Theorem 5.9. Let X follow the Modified Poisson Standard Uniform distribution with parameter λ_1 , and let Y follow Poisson Standard Uniform distribution with parameter λ_2 . Let $f_X(x)$ and $f_Y(y)$ denote the PDF's of X and Y, respectively. If $\lambda_2 < \lambda_1$, then $X \leq_{lr} Y$.

5.9 Incomplete Moments

The *r*th incomplete moment is given by $M_r(y) = \int_{-\infty}^y x^r f(x) dx$. For the Modified Poisson-X family of distributions, we have the following

Theorem 5.10. The rth incomplete moment for the Modified Poisson-X family of distributions, can be expressed as

$$M_r(y) = \frac{\lambda^{k+1}}{(e^{\lambda} - 1)k!} \sum_{k=0}^{\infty} \sum_{q=0}^{k} (-1)^q \binom{k}{q} \int_{-\infty}^{y} x^r f(x) F(x)^q dx,$$

where $\lambda \in (-\infty, 0) \cup (0, \infty)$, and the random variable X has PDF f(x) and CDF F(x).

5.10 Inequality Measures

The Lorenz curve, $L_F(y)$ for incomplete moments is defined as $L_F(y) = \frac{1}{\mu} \int_{-\infty}^{y} x f(x) dx$. For the Modified Poisson-X family of distributions, we have the following

Theorem 5.11. The Lorenz curve for the Modified Poisson-X family of distributions is given by

$$L_F(y) = \frac{\lambda^{k+1}}{\mu(e^{\lambda} - 1)k!} \sum_{k=0}^{\infty} \sum_{q=0}^{k} (-1)^q \binom{k}{q} \int_{-\infty}^{y} xf(x)F(x)^q dx,$$

where $\lambda \in (-\infty, 0) \cup (0, \infty)$, the random variable X has PDF f(x) and CDF F(x), and μ is the mean of the Poisson-X family.

The Bonferroni curve, $B_F(y)$ is defined as $B_F(y) = \frac{L_F(y)}{F(y)}$. For the Modified Poisson-X family of distributions, we have the following

Theorem 5.12. The Bonferroni curve of the Modified Poisson-X family can be expressed as

$$B_F(y) = \frac{\frac{\lambda^{k+1}}{\mu(e^{\lambda}-1)k!} \sum_{k=0}^{\infty} \sum_{q=0}^{k} (-1)^q {k \choose q} \int_{-\infty}^{y} xf(x)F(x)^q dx}{\frac{e^{\lambda} - \sum_{k=0}^{\infty} \sum_{q=0}^{k} \frac{\lambda^k}{k!} {k \choose q} (-1)^q F(x)^q}{e^{\lambda}-1}},$$

where $\lambda \in (-\infty, 0) \cup (0, \infty)$, the random variable X has PDF f(x) and CDF F(x), and μ is the mean of the Poisson-X family.

5.11 Mean Residual Life

The mean residual life is defined as $\bar{m}(y) = \frac{1}{1-F(y)} \left[\mu - \int_{-\infty}^{y} xf(x) dx \right] - y$. For the Modified Poisson-X family of distributions, we have the following

Theorem 5.13. The mean residual life for the Modified Poisson-X family of distributions is given by

$$\bar{m}(y) = \left(1 - \frac{e^{\lambda} - \sum_{k=0}^{\infty} \sum_{q=0}^{k} \frac{\lambda^{k}}{k!} {k \choose q} (-1)^{q} F(y)^{q}}{e^{\lambda} - 1}\right)^{-1} \times \left[\mu - \frac{\lambda^{k+1}}{(e^{\lambda} - 1)k!} \sum_{k=0}^{\infty} \sum_{q=0}^{k} (-1)^{q} {k \choose q} \int_{-\infty}^{y} xf(x)F(x)^{q} dx\right] - y,$$

where $\lambda \in (-\infty, 0) \cup (0, \infty)$, the random variable X has PDF f(x) and CDF F(x), and μ is the mean of the Poisson-X family.

5.12 Order Statistics

The pdf for the *p*th order statistics $X_{p:n}$ of an independent identically distributed random sample, X_1, X_2, \dots, X_n , of size $n, f_{X_{p:n}}(x)$, is given by

$$f_{X_{p:n}}(x) = \frac{n!}{(p-1)!(n-p)!} F(x)^{p-1} (1-F(x))^{n-p} f(x)$$

for $p = 1, 2, \cdots, n$.

Lemma 5.14. The pdf for the pth order statistics $X_{p:n}$ of an independent identically distributed random sample, X_1, X_2, \dots, X_n , of size n, $f_{X_{p:n}}(x)$, can be expressed as

$$f_{X_{p:n}}(x) = \sum_{j=0}^{n-p} \omega_j f(x) F(x)^{p-1+j},$$

where

$$\omega_j = \frac{n!}{(p-1)!(n-p)!} \binom{n-p}{j} (-1)^j.$$

Lemma 5.15. Let F(x) be given by the CDF of the Modified Poisson-X family of distributions. Then $F(x)^{p-1+j}$ can be expressed as

$$\sum_{v=0}^{p-1+j}\sum_{m=0}^{\infty}\omega_{v,m}F(x)^m,$$

where

$$\omega_{v,m} = \frac{e^{\lambda(p-1+j)}}{(e^{\lambda}-1)^{p-1+j}} {p-1+j \choose v} \frac{(-1)^{m+v} v^m \lambda^m}{m!}$$
$$\lambda \in (-\infty, 0) \cup (0, \infty)$$

and F(x) is some baseline CDF.

Corollary 5.16. The PDF in Theorem 5.2 can be expressed as

$$\sum_{k=0}^{\infty} \sum_{q=0}^{k} \omega_{k,q} f(x) F(x)^{q},$$

where

$$\omega_{k,q} = \frac{\lambda^{k+1}}{(e^{\lambda} - 1)k!} (-1)^q \binom{k}{q}$$
$$\lambda \in (-\infty, 0) \cup (0, \infty)$$

and F(x) is some baseline CDF, and f(x) is some baseline PDF.

By combining Lemma 5.14, Lemma 5.15, and Corollary 5.16, we get the following

Theorem 5.17. The pdf, $f_{X_{p:n}}(x)$, for the pth order statistics $X_{p:n}$ of an independent identically distributed random sample, X_1, X_2, \dots, X_n , of size n, from the Modified Poisson-X family is given by

$$f_{X_{p:n}}(x) = \sum_{j=0}^{n-p} \sum_{v=0}^{p-1+J} \sum_{m,k=0}^{\infty} \sum_{q=0}^{k} \omega_j \ \omega_{v,m} \ \omega_{k,q} f(x) F(x)^{m+q}.$$

5.13 Moments of Order Statistics

The *r*th non-central moments of the *p*th order statistics is given by

$$E(X_{p:n}^r) = \int_{-\infty}^{\infty} x^r f_{X_{p:n}}(x) dx$$

For the Poisson-X family of distributions we have the following using Theorem 5.17.

Theorem 5.18. The rth noncentral moments of the pth order statistics for the Poisson-X family is given by

$$E(X_{p:n}^{r}) = \sum_{j=0}^{n-p} \sum_{v=0}^{p-1+J} \sum_{m,k=0}^{\infty} \sum_{q=0}^{k} \omega_{j} \ \omega_{v,m} \ \omega_{k,q} \int_{-\infty}^{\infty} x^{r} f(x) F(x)^{m+q} dx$$

6 Parameter Estimation

The method of maximum likelihood is used in this paper to estimate model parameters. Here we discuss this method for the Modified Poisson-X family of distributions. Suppose x_1, x_2, \dots, x_n is a random sample of size n from the Modified Poisson-X family of distributions. It can be shown that the total log-likelihood function is given by

$$l = n \ln(\lambda) - n \ln(e^{\lambda} - 1) + \sum_{i=1}^{n} \ln f(x_i; \psi) + n\lambda - \lambda \sum_{i=1}^{n} F(x_i; \psi),$$

where ψ is a vector of parameters associated with the baseline distribution. Partial differentiation of the total log-likelihood function with respect to model parameters gives the following as the score functions

$$\frac{\partial l}{\partial \lambda} = \frac{n}{\lambda} - \frac{e^{\lambda}}{e^{\lambda} - 1} + n - \sum_{i=1}^{n} F(x_i; \psi)$$
$$\frac{\partial l}{\partial \psi} = \sum_{i=1}^{n} \frac{\frac{\partial f(x_i; \psi)}{\partial \psi}}{f(x_i; \psi)} - \lambda \sum_{i=1}^{n} \frac{\partial F(x_i; \psi)}{\partial \psi}.$$

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Equating the score functions to zero and numerically solving the system of equations using techniques such as the quasi Newton-Raphson method, gives the maximum likelihood estimates for the model parameters. Let $\Delta = (\lambda; \psi)$, for the purposes of constructing confidence intervals for the parameters in the Poisson-X family of distributions, the observed information matrix, call it $J(\Delta)$, can be used due to the complex nature of the expected information matrix. The observed information matrix is given by

$$J(\triangle) = - \begin{bmatrix} \frac{\partial^2 lnL}{\partial^2 \lambda} & \frac{\partial^2 lnL}{\partial \lambda \partial \psi} \\ & \frac{\partial^2 lnL}{\partial^2 \psi} \end{bmatrix}.$$

The elements of the observed information matrix are given below

$$\frac{\partial^2 lnL}{\partial^2 \lambda} = \frac{-n}{\lambda} - \frac{1}{2 - 2\cosh(\lambda)}$$

$$\frac{\partial^2 lnL}{\partial \lambda \partial \psi} = -\sum_{i=1}^n \frac{\partial F(x_i;\psi)}{\partial \psi}$$

$$\frac{\partial^2 lnL}{\partial^2 \psi} = \frac{\left(\frac{\partial f(x_i;\psi)}{\partial \psi}\right)^2 - f(x_i;\psi)\frac{\partial^2 f(x_i;\psi)}{\partial \psi}}{f(x_i;\psi)^2)}.$$

When the usual regularity conditions are satisfied and that the parameters are within the interior of the parameter space, but not on the boundary, the distribution of $\sqrt{n}(\widehat{\Delta} - \Delta)$ converges to the multivariate normal distribution $N_{p+1}(0, I^{-1}(\Delta))$, where $I(\Delta)$ is the expected information matrix, and it is assumed that $\psi = (\psi_1, \cdots, \psi_p)$. The asymptotic behavior remains valid when $I(\Delta)$ is replaced by the observed information matrix evaluated at $J(\widehat{\Delta})$. The asymptotic multivariate normal distribution $N_{p+1}(0, J^{-1}(\widehat{\Delta}))$ is a very useful tool for constructing an approximate $100(1 - \xi)\%$ two-sided confidence intervals for the model parameters, where ξ is the significance level.

7 Monte Carlo Simulation Study

In this section we show that the method of maximum likelihood is adequate in estimating the parameters in the power series family of inverted exponentiated generalized distributions. For this, a Monte Carlo simulation study is carried out to assess the performance of the estimation method in the Modified Poisson inverted exponentiated generalized distribution (MPIEG). Samples of sizes 200, 400, 500, and 700, are drawn from the MPIEG distribution, and the samples have been drawn for the following set of parameters

- (a) <u>Set I:</u> $(\alpha, \beta, \lambda) = (8.3, 20.5, -2.9)$
- (b) <u>Set II:</u> $(\alpha, \beta, \lambda) = (20.5, 8.3, 2.9)$
- (c) <u>Set III:</u> $(\alpha, \beta, \lambda) = (8.3, 8.3, -2.9)$

The maximum likelihood estimators for the parameters α , β , and λ are obtained. The procedure has been repeated 400 times, and the mean and standard deviation for the estimates are computed, and the results are summarized in Tables 4-6 for each of sets I, II, and III, respectively, considered above.

	Parameter λ		
Sample Size	Average Estimate	Standard Deviation	
200	-3.061675	1.885471	
400	-2.623562	1.344442	
500	-2.731107	1.205112	
700	-2.729688	1.010639	
	Parameter α		
Sample Size	Average Estimate	Standard Deviation	
200	8.592962	2.127773	
400	8.875303	1.721993	
500	8.715073	1.582886	
700	8.662126	1.315252	
Parameter β			
Sample Size	Average Estimate	Standard Deviation	
200	22.96349	9.664607	
400	23.41261	7.411761	
500	22.77176	6.893993	
700	22.36556	5.542204	

Table 4: Result of simulation study for Set I.

From the table above, we find that the simulated estimates are close to the true values of the parameters and hence the estimation method is adequate. We have also observed that the estimated standard deviation consistently decrease with increasing sample size as seen in the graphs below.



Table 5: Decreasing standard deviation for increasing sample size.

	Parameter λ		
Sample Size	Average Estimate	Standard Deviation	
200	2.90078	2.045452	
400	3.0843	1.562558	
500	2.975228	1.344621	
700	3.060976	1.263785	
	Parai	meter α	
Sample Size	Average Estimate	Standard Deviation	
200	20.00319	1.824284	
400	20.24646	1.194761	
500	20.27795	0.7811548	
700	20.33272	0.7474834	
	Parameter β		
Sample Size	Average Estimate	Standard Deviation	
200	8.954466	3.60614	
400	8.331257	2.756652	
500	8.528862	2.502422	
700	8.321384	2.327853	

Table 6: Result of simulation study for Set II.

From the table above, we find that the simulated estimates are close to the true values of the parameters and hence the estimation method is adequate. We have also observed that the estimated standard deviation consistently decrease with increasing sample size as seen in the graphs below.



Table 7: Decreasing standard deviation for increasing sample size.

	Parameter λ		
Sample Size	Average Estimate	Standard Deviation	
200	-2.852931	1.944682	
400	-2.690511	1.366186	
500	-2.801686	1.230114	
700	-2.726701	1.07826	
	Parai	meter α	
Sample Size	Average Estimate	Standard Deviation	
200	8.867683	2.359042	
400	8.864493	1.877261	
500	8.68127	1.731915	
700	8.727292	1.526116	
	Parameter β		
Sample Size	Average Estimate	Standard Deviation	
200	8.863993	2.245196	
400	8.811248	1.671934	
500	8.682323	1.578819	
700	8.701399	1.346391	

Table 8: Result of simulation study for Set III.

From the table above, we find that the simulated estimates are close to the true values of the parameters and hence the estimation method is adequate. We have also observed that the estimated standard deviation consistently decrease with increasing sample size as seen in the graphs below.



Table 9: Decreasing standard deviation for increasing sample size.

Overall the simulation study conducted, indicated that using the method of maximum likelihood in estimating model parameters is adequate.

8 Application to Real-Life Data

Here we demonstrate usefulness of the new family to the breaking stress of carbon fibers data, Table 2 [10]. The PDF's and CDF's of the distributions considered are already given in Section 4. We assume the modified parameter and domain space of Section 4. Using the R software, we report below in Table 10, the estimates for the parameters in each of the four distributions alongside their standard errors.

Distribution	Parameters	Estimates	Standard error
MPIEG	$\hat{\alpha}$	8.3575	1.7525
	\hat{eta}	20.4989	8.1846
	$\hat{\lambda}$	-3.0013	1.2541
MGIEG	$\hat{\alpha}$	5.1853	1.9665
	\hat{eta}	15.4842	5.7644
	$\hat{\lambda}$	-30.7747	40.2004
MBIEG	$\hat{\alpha}$	10.23557	1.53244
	\hat{eta}	25.79400	10.06697
	$\hat{\lambda}$	-0.74807	0.19661
MLIEG	\hat{lpha}	8.9122	1.2876
	\hat{eta}	34.1047	10.0191
	$\hat{\lambda}$	-53.8299	74.1666

Table 10: Estimates for the parameter of fitted distribution.

The fitted CDF's to the carbon fibers data are shown below



Figure 6: The fitted CDFs of MBIEG(purple), M LIEG(green), MPIEG (red), and MGIEG(blue) to the empirical distribution of Table 2 [10].



and the fitted PDF's are shown below

Figure 7: The fitted PDFs of MBIEG(purple), MLIEG(green), MPIEG (red), and MGIEG(blue) to the histogram of Table 2 [10].

The measures of goodness of fit we consider include Akaike information criterion (AIC), Bayesian information criterion (BIC), -2Log-Likelihood, and second-order Akaike Information Criterion (AICc) and they are reported in Table 11. Whilst it appears from the fits above, that all the distributions are competitive in fitting the breaking stress of carbon fibers data, Table 11 reveals that the MGIEG distribution is most compatible with this data set, and hence can be considered the best in this instance.

Distribution	AIC	BIC	AICc	-2Log-Likelihood
MPIEG	183.5427	190.1117	183.9298	177.5427
MGIEG	178.0328	184.6018	178.4199	172.0328
MBIEG	186.7326	193.3016	187.1197	180.7326
MLIEG	181.4471	188.016	181.8342	175.4471

Table 11: Goodness-of-fit measures.

9 Some Characterization Theorems

The characterization of statistical distributions plays a major role in stochastic modeling. In this section we present some characterizations of the Modified Poisson-X family of distributions. Our first characterization theorem is based on a simple relationship between two truncated moments, and for related works in this direction, the reader is referred to [11]-[16].

At first, we recall the following which will be useful in Section 9.1

Theorem 9.1. [12] Let $(\Omega, \Sigma, \mathbb{P})$ be a given probability space, and let I = [a, b] be an interval for some a < b $(a = -\infty, b = \infty$ might as well be allowed). Let $X : \Omega \mapsto I$ be a continuous random variable with probability distribution function F, and let q_1 and q_2 be two real functions on I such that

$$\mathbb{E}[q_1(X)|X \ge x] = \mathbb{E}[q_2(X)|X \ge x]\eta(x), \ x \in I,$$

is defined with some real function η . Assume that $q_1, q_2 \in C^1(I)$, and $\eta \in C^2(I)$, and F is twice continuously differentiable and strictly monotone increasing on the set I. Finally, assume that the equation $\eta q_2 = q_1$ has no real solutions in the interior of I. Then F is uniquely determined by the functions q_1, q_2, η . In particular,

$$F(x) = \int_{a}^{x} C \left| \frac{\eta'(u)}{\eta(u)q_{2}(u) - q_{1}(u)} \right| exp(-s(u))du,$$

where the function s is a solution of the differential equation

$$s' = \frac{\eta' q_2}{\eta q_2 - q_1}$$

and C is a constant chosen to make $\int_I dF = 1$.

Remark 9.2. The characterization based on the ratio of two truncated moments is stable in the sense of weak convergence, and for more details see [17].

In Section 9.2 we employ a single function ψ of X and state characterization results in terms of $\psi(X)$. At first we recall the following two results that will be useful in the sequel. **Proposition 9.3.** [18] Let $X : \Omega \mapsto (a, b)$ be a continuous random variable with CDF F. Let $\psi(x)$ be a differentiable function on (a, b) with $\lim_{x\to a^+} \psi(x) = \delta > 1$ and

$$\lim_{x \to b^-} \psi(x) = \infty.$$

Then

$$\mathbb{E}[(\psi(X))^{\delta}|X \le x] = \delta(\psi(x))^{\delta-1}, \ x \in (a,b),$$

implies

$$\psi(x) = \delta[1 - (F(x))^{\frac{1}{1-\delta}}]^{-1}, \ x \in (a,b).$$

Proposition 9.4. [18] Let $X : \Omega \mapsto (a, b)$ be a continuous random variable with CDF F. Let $\psi_1(x)$ be a differentiable function on (a, b) with $\lim_{x\to a^+} \psi_1(x) = \frac{\delta}{2} > \frac{1}{2}$ and

$$\lim_{x \to b^-} \psi_1(x) = \infty.$$

Then

$$\mathbb{E}[(\psi_1(X))^{\delta}|X \le x] = \delta(\psi_1(x))^{\delta-1}, \ x \in (a,b),$$

implies

$$\psi_1(x) = \delta [1 + (1 - F(x))^{\frac{1}{1 - \delta}}]^{-1}, \ x \in (a, b)$$

9.1 Characterization Based on Two Truncated Moments

The main result here is the following which we state without proof

Proposition 9.5. Let $X : \Omega \mapsto \mathbb{R}$ be a continuous random variable, and let $q_2(x) = 1$ and

$$q_1(x) = 1 - \frac{e^{\lambda(1-F(x))} - 1}{e^{\lambda} - 1},$$

where $\lambda \in (-\infty, 0) \cup (0, \infty)$ and F(x) is some baseline CDF. The PDF of X is

$$\frac{\lambda}{e^{\lambda}-1}f(x)e^{\lambda(1-F(x))},$$

where f(x) is the PDF of the baseline distribution iff the function η of Theorem 8.1 is given by

$$\eta(x) = \frac{1}{2} - \frac{e^{\lambda(1 - F(x))} - 1}{2(e^{\lambda} - 1)}.$$

If q_2 is given by the previous Proposition, then we have the following

Corollary 9.6. Let $X : \Omega \mapsto \mathbb{R}$ be a continuous random variable. The PDF of X is

$$\frac{\lambda}{e^{\lambda}-1}f(x)e^{\lambda(1-F(x))}$$

iff there exists functions q_1 and η defined in Theorem 8.1 satisfying the following differential equation

$$\frac{\eta'(x)}{\eta(x) - q_1(x)} = \frac{\frac{\lambda}{e^{\lambda} - 1} f(x) e^{\lambda(1 - F(x))}}{1 - \frac{e^{\lambda(1 - F(x))} - 1}{e^{\lambda} - 1}}$$

Remark 9.7. The general solution of the above differential equation is given by

$$\eta(x) = \left(1 - \frac{e^{\lambda(1 - F(x))} - 1}{e^{\lambda} - 1}\right)^{-1} \left[\int q_1(x) \frac{\lambda}{e^{\lambda} - 1} f(x) e^{\lambda(1 - F(x))} dx + D\right],$$

where D is a constant. One set of appropriate functions is given by the previous Proposition with D = 0.

9.2 Characterization Based on Conditional Expectation

The main results here are as follows.

9.2.1 Characterization based on Proposition 9.3

Take $(a, b) = (0, \infty)$ and

$$\psi(x) = \delta \left[2 - \frac{e^{\lambda(1 - F(x))} - 1}{e^{\lambda} - 1} \right]^{-1}$$

gives a characterization of the Modified Poisson-X family of distributions.

9.2.2 Characterization based on Proposition 9.4

Take $(a, b) = (0, \infty)$ and

$$\psi_1(x) = \delta \left[1 + \left(\frac{e^{\lambda(1 - F(x))} - 1}{e^{\lambda} - 1} \right)^{\frac{1}{\delta - 1}} \right]^{-1}$$

gives a characterization of the Modified Poisson-X family of distributions.

10 Further Recommendations

The Chen distribution [19] has CDF given by

$$G(t) = 1 - e^{\gamma(1 - e^{t^{\beta}})},$$

where $\gamma, \beta, t > 0$. We suggest obtaining some properties and applications of a so-called power seres inverted Chen class of distributions (using the CDF of Section 1 which is based on the stochastic representation $X_1 = min\{X_1, \dots, X_n\}$) which is given by

$$1 - \frac{C(\lambda(1 - K(x)))}{C(\lambda)}$$

where C is some useful quantity from Table 1, and

$$K(x) = 1 - G\left(\frac{1}{x+1}\right)$$

with G being the CDF of the Chen distribution.

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